## Censored and Truncated Outcome Panel Data Models

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### Censored Data

- y<sub>it</sub> is censored when it is partly continuous but has positive probability mass at one or more points.
  - For example,  $y_{it}$  is continuous when  $y_{it} > 0$  but has a large mass at  $y_{it} = 0$ .
- We can sometimes think of the underlying model as:

$$y_{it}^{\star} = \alpha_i + \mathbf{x}_{it}^{\prime} \boldsymbol{\beta} + \varepsilon_{it}$$

but we observe:

$$y_{it} = \begin{cases} y_{it}^{\star} & \text{if } y_{it}^{\star} > \underline{y} \\ \underline{y} & \text{if } y_{it}^{\star} \le \underline{y} \end{cases} \quad \text{or} \quad y_{it} = \begin{cases} \overline{y} & \text{if } y_{it}^{\star} \ge \overline{y} \\ y_{it}^{\star} & \text{if } y_{it}^{\star} < \overline{y} \end{cases}$$

For example, top-coded income.

- Other times we can think of  $\overline{y}$  or y as a corner solution of an optimization problem.
  - For example, hours worked, firm expenditure on R&D.

## Histogram of censored $y_{it}$ left of zero



#### Truncated Data

- Our sample may be **truncated**, where our sample only has observations where  $y_{it} > \underline{y}$  or  $y_{it} < \overline{y}$
- For example, we may only observe people who work.

# Histogram of truncated $y_{it}$



### Models in this Topic

- Static Censored Random Effects
- Static Truncated Fixed Effects
- It is possible to estimate Static & Dynamic Censored Fixed Effects models, but we won't cover them here.

#### Censored Data: Panel Random Effects Tobit Model

• We consider the left-censored data case where y = 0.

We observe:

$$y_{it} = egin{cases} y_{it}^\star & ext{ if } y_{it}^\star > 0 \ 0 & ext{ if } y_{it}^\star \leq 0 \end{cases}$$

- Let  $d_{it} = \mathbb{1} \{ y_{it} > 0 \}.$
- If  $\varepsilon_{it} \sim \mathcal{N}(0, \sigma_{\varepsilon}^2)$ , then using  $\varepsilon_{it} = y_{it}^{\star} \alpha_i \mathbf{x}'_{it}\beta$ , the joint conditional density of  $\mathbf{y}_i = (y_{i1}, \dots, y_{iT})$  is

$$f\left(\boldsymbol{y}_{i} \left| \boldsymbol{X}_{i}, \alpha_{i}, \boldsymbol{\beta}, \sigma_{\varepsilon}^{2} \right. \right) = \prod_{t=1}^{T} \left[ \frac{1}{\sigma_{\varepsilon}} \phi\left( \frac{y_{it} - \alpha_{i} - \boldsymbol{x}_{it}^{\prime} \boldsymbol{\beta}}{\sigma_{\varepsilon}} \right) \right]^{d_{it}} \left[ 1 - \Phi\left( \frac{\alpha_{i} + \boldsymbol{x}_{it}^{\prime} \boldsymbol{\beta}}{\sigma_{\varepsilon}} \right) \right]^{1 - d_{it}}$$

where  $\mathbf{X}_i = (\mathbf{x}_{i1}, \dots, \mathbf{x}_{iT})$  and  $\phi$  and  $\Phi$  are the pdf and cdf of the standard normal distribution respectively.

#### Censored Data: Panel Random Effects Tobit Model

▶ If we model  $\alpha_i \sim \mathcal{N}(0, \sigma_{\alpha}^2)$ , then we can integrate out the  $\alpha_i$ :

$$f\left(\boldsymbol{y}_{i} \left| \boldsymbol{X}_{i}, \boldsymbol{\beta}, \sigma_{\varepsilon}^{2}, \sigma_{\alpha}^{2} \right.\right) = \int_{-\infty}^{\infty} f\left(\boldsymbol{y}_{i} \left| \boldsymbol{X}_{i}, \alpha_{i}, \boldsymbol{\beta}, \sigma_{\varepsilon}^{2} \right.\right) \frac{1}{\sqrt{2\pi\sigma_{\alpha}^{2}}} \exp\left(\frac{-\alpha_{i}^{2}}{2\sigma_{\alpha}^{2}}\right) d\alpha_{i}$$

- There is no closed-form solution for the likelihood and therefore needs to be computed using simulation methods.
- We can perform the same change of variables as with the probit random effects and approximate the integral with Gauss-Hermite quadrature.

## Truncated Fixed Effects: Only observe $y_{it}$ when $y_{it}^{\star} > 0$

- When data are truncated, we cannot eliminate the fixed effects by differencing or mean differencing.
- ► For observed *y*<sub>*it*</sub>:

$$y_{it} = \mathbb{E}\left[y_{it}^{\star} | \mathbf{x}_{it}, \alpha_i, y_{it}^{\star} > 0\right] + \nu_{it}$$
  
=  $\alpha_i + \mathbf{x}'_{it} \boldsymbol{\beta} + \mathbb{E}\left[\varepsilon_{it} | \varepsilon_{it} > -\alpha_i - \mathbf{x}'_{it} \boldsymbol{\beta}\right] + \nu_{it}$ 

• Consider the T = 2 case. Taking differences:

$$y_{i2} - y_{i1} = (\mathbf{x}_{i2} - \mathbf{x}_{i1})' \boldsymbol{\beta} + \mathbb{E} [\varepsilon_{i2} | \varepsilon_{i2} > -\alpha_i - \mathbf{x}'_{i2} \boldsymbol{\beta}] - \mathbb{E} [\varepsilon_{i1} | \varepsilon_{i1} > -\alpha_i - \mathbf{x}'_{i1} \boldsymbol{\beta}] + \nu_{i2} - \nu_{i1}$$

▶ In general, this still depends on  $\alpha_i$  (unless  $\mathbf{x}_{i1} = \mathbf{x}_{i2}$ )

# Honoré (1992)

Suppose we restricted our analysis to observations satisfying

$$y_{i1} \ge -(\mathbf{x}_{i2} - \mathbf{x}_{i1})' \boldsymbol{\beta}$$
 and  $y_{i2} \ge (\mathbf{x}_{i2} - \mathbf{x}_{i1})' \boldsymbol{\beta}$ 

Suppose that  $(\mathbf{x}_{i2} - \mathbf{x}_{i1})' \beta > 0$  ( $\exists$  similar argument for the opposite case). Then:

$$\mathbb{E}\left[y_{i2}|\mathbf{x}_{i2},\alpha_{i},y_{i2} \geq (\mathbf{x}_{i2}-\mathbf{x}_{i1})'\beta\right]$$
  
=  $\alpha_{i} + \mathbf{x}'_{i2}\beta + \mathbb{E}\left[\varepsilon_{i2}|\varepsilon_{i2} \geq -\alpha_{i} - \mathbf{x}'_{i2}\beta + (\mathbf{x}_{i2}-\mathbf{x}_{i1})'\beta\right]$   
=  $\alpha_{i} + \mathbf{x}'_{i2}\beta + \mathbb{E}\left[\varepsilon_{i2}|\varepsilon_{i2} \geq -\alpha_{i} - \mathbf{x}'_{i1}\beta\right]$ 

Since  $(\mathbf{x}_{i2} - \mathbf{x}_{i1})' \beta > 0$ , the restriction doesn't bind for  $y_{i1}$ :

$$\mathbb{E}\left[y_{i1}|\boldsymbol{x}_{i1},\alpha_{i},y_{i1}\geq-(\boldsymbol{x}_{i2}-\boldsymbol{x}_{i1})'\boldsymbol{\beta}\right]=\mathbb{E}\left[y_{i1}|\boldsymbol{x}_{i1},\alpha_{i},y_{i1}\geq0\right]$$
$$=\alpha_{i}+\boldsymbol{x}_{i1}'\boldsymbol{\beta}+\mathbb{E}\left[\varepsilon_{i1}|\varepsilon_{i1}\geq-\alpha_{i}-\boldsymbol{x}_{i1}'\boldsymbol{\beta}\right]$$

# Honoré (1992)

• If we assume the  $\varepsilon_{it} | \mathbf{x}_{it}, \alpha_i$  are iid, then:

$$\mathbb{E}\left[\varepsilon_{i1}|\varepsilon_{i1}\geq-\alpha_{i}-\mathbf{x}_{i1}'\boldsymbol{\beta}\right]=\mathbb{E}\left[\varepsilon_{i2}|\varepsilon_{i2}\geq-\alpha_{i}-\mathbf{x}_{i1}'\boldsymbol{\beta}\right]$$

#### Therefore

$$\mathbb{E}\left[y_{i1}|\mathbf{x}_{i1},\alpha_{i},y_{i1}\geq-\left(\mathbf{x}_{i2}-\mathbf{x}_{i1}\right)'\beta\right]=\alpha_{i}+\mathbf{x}_{i1}'\beta+\mathbb{E}\left[\varepsilon_{i1}|\varepsilon_{i1}\geq-\alpha_{i}-\mathbf{x}_{i1}'\beta\right]\\\mathbb{E}\left[y_{i2}|\mathbf{x}_{i2},\alpha_{i},y_{i2}\geq\left(\mathbf{x}_{i2}-\mathbf{x}_{i1}\right)'\beta\right]=\alpha_{i}+\mathbf{x}_{i2}'\beta+\mathbb{E}\left[\varepsilon_{i1}|\varepsilon_{i1}\geq-\alpha_{i}-\mathbf{x}_{i1}'\beta\right]$$

$$\mathbb{E}\left[y_{i2} - y_{i1} | \mathbf{x}_{i1}, \mathbf{x}_{i2}, \alpha_i, y_{i1} \ge -(\mathbf{x}_{i2} - \mathbf{x}_{i1})' \beta, y_{i2} \ge (\mathbf{x}_{i2} - \mathbf{x}_{i1})' \beta\right] \\ = (\mathbf{x}_{i2} - \mathbf{x}_{i1})' \beta$$

which no longer depends on the fixed effect  $\alpha_i$ .

• This only requires the iid assumption. We don't assume anything about the distribution of  $\varepsilon_{it}$ .

Honoré (1992): Estimation when T = 2

• If we knew the true  $\beta$ , we could estimate it with OLS in the model:

$$y_{i2} - y_{i1} = (\mathbf{x}_{i2} - \mathbf{x}_{i1})' \boldsymbol{\beta} + \nu_{i2} - \nu_{i1}$$

using the sample where:

►  $y_{i1} \ge -(x_{i2} - x_{i1})' \beta$ ►  $y_{i2} \ge (x_{i2} - x_{i1})' \beta$ 

 $\blacktriangleright$  However, we do not know  $\beta$ .

## Honoré (1992): Estimation

► Honoré (1992) proposes the following objective:

$$\begin{split} \widehat{\boldsymbol{\beta}} &= \arg\min_{\boldsymbol{\beta}} \sum_{i=1}^{N} \left\{ \begin{bmatrix} y_{i2} - y_{i1} - (\boldsymbol{x}_{i2} - \boldsymbol{x}_{i1})' \, \boldsymbol{\beta} \end{bmatrix}^{2} \\ &\times \mathbb{1} \left\{ y_{i1} \ge -(\boldsymbol{x}_{i2} - \boldsymbol{x}_{i1})' \, \boldsymbol{\beta}, y_{i2} \ge (\boldsymbol{x}_{i2} - \boldsymbol{x}_{i1})' \, \boldsymbol{\beta} \right\} \\ &+ y_{i1}^{2} \mathbb{1} \left\{ y_{i1} \ge -(\boldsymbol{x}_{i2} - \boldsymbol{x}_{i1})' \, \boldsymbol{\beta}, y_{i2} < (\boldsymbol{x}_{i2} - \boldsymbol{x}_{i1})' \, \boldsymbol{\beta} \right\} \\ &+ y_{i2}^{2} \mathbb{1} \left\{ y_{i1} < -(\boldsymbol{x}_{i2} - \boldsymbol{x}_{i1})' \, \boldsymbol{\beta}, y_{i2} \ge (\boldsymbol{x}_{i2} - \boldsymbol{x}_{i1})' \, \boldsymbol{\beta} \right\} \end{split}$$

# Honoré (1992): Estimation

Why the 2nd and 3rd term?

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- Consider the single regressor case.
- Suppose we estimated  $\beta$  by minimizing:

$$\sum_{i=1}^{N} \left[ y_{i2} - y_{i1} - (x_{i2} - x_{i1}) \beta \right]^2 \mathbb{1} \left\{ y_{i1} \ge - (x_{i2} - x_{i1}) \beta, y_{i2} \ge (x_{i2} - x_{i1}) \beta \right\}$$

- ▶ By setting  $\beta$  sufficiently large or small, no  $y_{i1}$  and  $y_{i2}$  will satisfy  $y_{i1} \ge -(x_{i2} x_{i1})\beta$  and  $y_{i2} \ge (x_{i2} x_{i1})\beta$  simultaneously for any *i*.
- ▶ The objective function would then be zero, its lowest possible value.
- The inclusion of the 2nd and 3rd term excludes these trivial solutions.

## Reading and References

- Cameron and Trivedi 23.5 for Random effects Tobit.
- Hsiao 8.4 and Honoré (1992) for Truncated Fixed Effects.

#### **References:**

HONORÉ, B. E. (1992): "Trimmed LAD and least squares estimation of truncated and censored regression models with fixed effects," *Econometrica*, 533–565.